

# PrIC3 : Property Directed Reachability for MDPs



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### Standard IC3 [Bradley 2011] [Eén *et al.* 2011]

- Verifies or refutes **reachability properties** of transition systems:
  - “ Given a transition system, is some **Bad** state reachable? “
- Was a **breakthrough** for hardware verification
- Applications: Verification of **hardware, software, hybrid systems, ...**

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### PrIC3

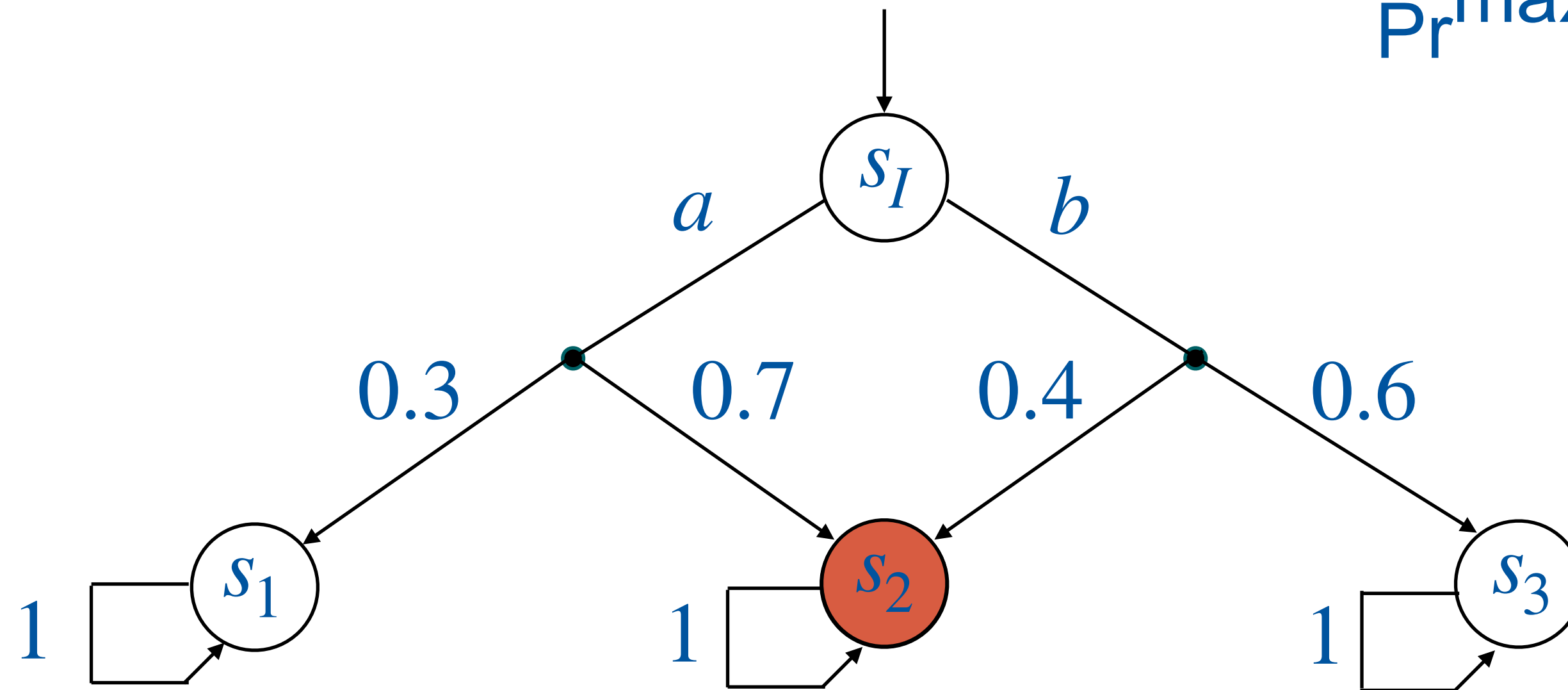
“ Given a Markov decision process, is the maximal probability to reach some **Bad** state at most  $\lambda \in [0,1]$  ? “

- Applications: Scalable verification of probabilistic systems, **probabilistic programs, ...**

## Markov Decision Processes

$$\mathcal{M} = (S, s_I, \text{Act}, P) \quad \text{Bad} \subseteq S \quad \lambda \in [0,1]$$

$$\Pr^{\max}(s_I \models \diamond \text{Bad}) = 0.7 \leq \lambda ?$$

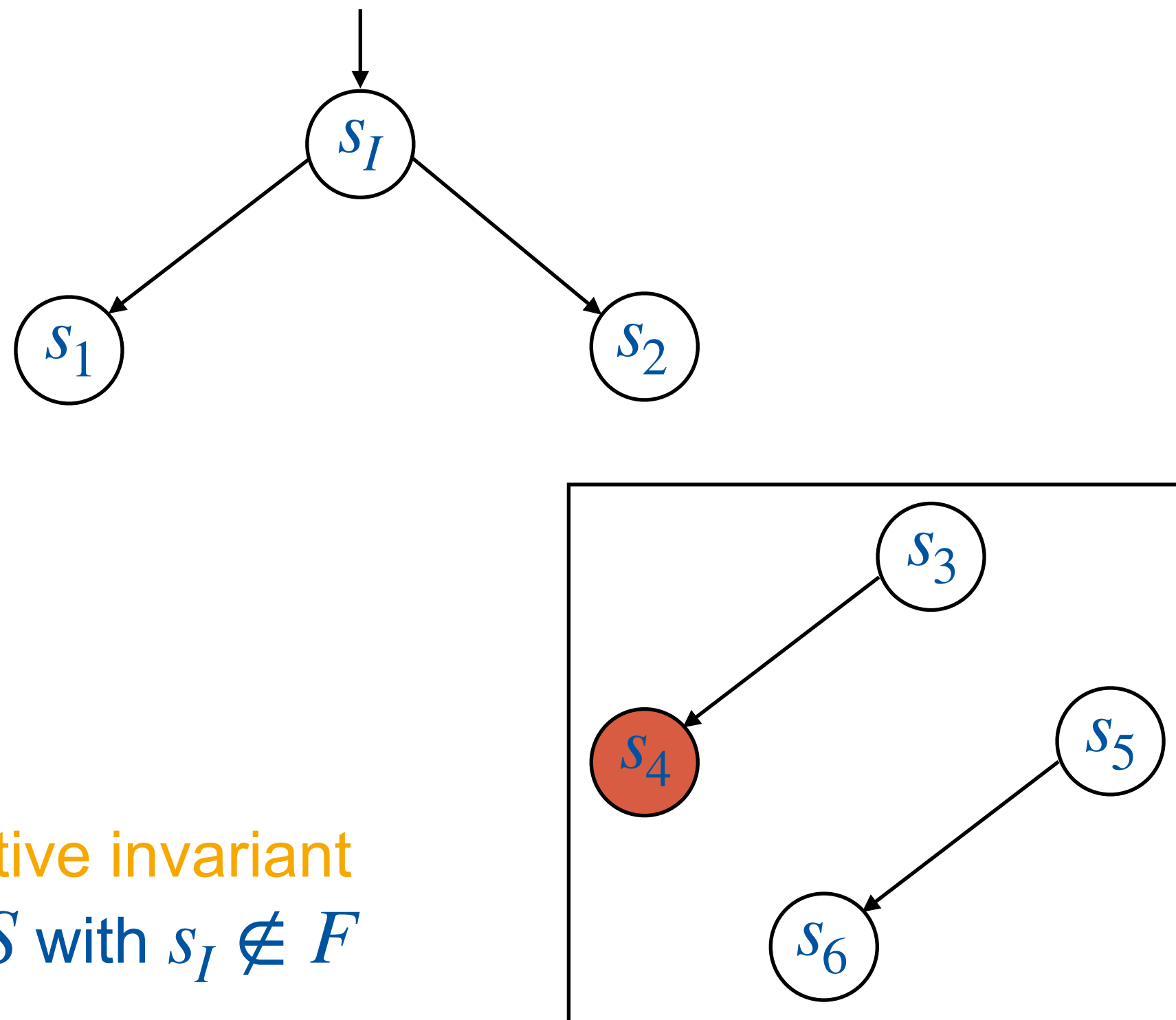


## Contributions

- Understand IC3 on the level of sets/functions rather than formulae/SAT queries
- A PrIC3 framework **conservatively extending** (reverse) IC3
- Prototypical **implementation** and **empirical evaluation**
  - Operate on program level (PRISM) by means of an **SMT encoding**
  - Repushing obligations, propagation, (first ideas on) **generalization**

# Proving Unreachability

TS =  $(S, s_I, T)$  Bad  $\subseteq S$

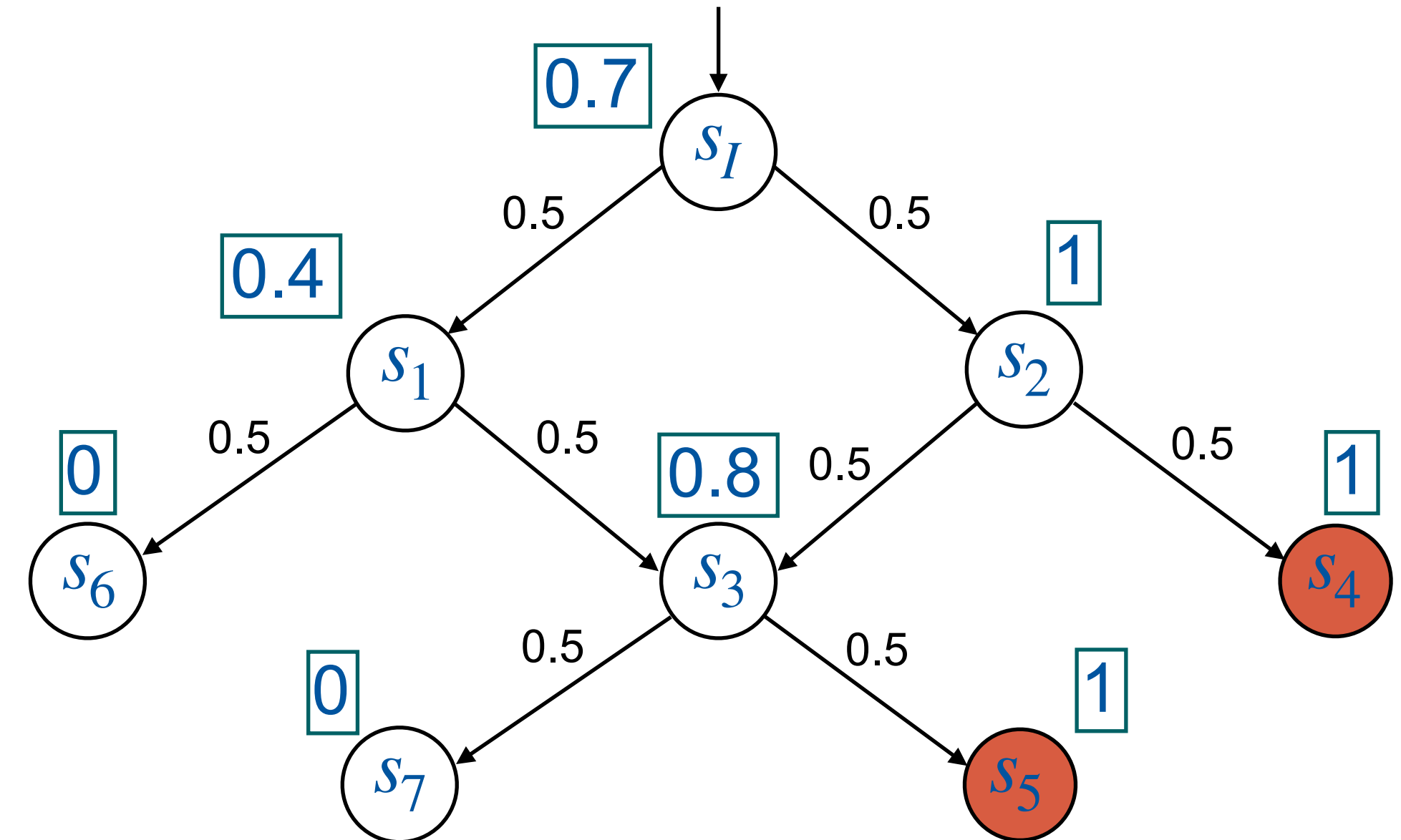


Inductive invariant  
 $F \subseteq S$  with  $s_I \notin F$

or:  
 $F: S \rightarrow \{0,1\}$  with  $F[s_I] = 0$

MC =  $(S, s_I, P)$  Bad  $\subseteq S$   $\lambda = 0.7$

$\Pr(s_I \models \diamond \text{Bad}) = 0.5$



$$\sum_{s' \in S} P(s, s') \cdot F[s'] \leq F[s]$$

Inductive invariant  
 $F: S \rightarrow [0,1]$  with  $F[s_I] \leq \lambda$

## The Theory underlying (Pr)IC3

$$\text{TS} = (S, s_I, T) \quad \text{Bad} \subseteq S$$

Call  $F: S \rightarrow \{0,1\}$  a **frame**.

Frames are **partially ordered** by

$$F \leq F' \quad \text{iff} \quad \forall s: F[s] \leq F'[s] .$$

$$\Phi: 2^S \rightarrow 2^S,$$

$$\Phi(F) = \text{Bad} \cup \text{Pred}(F)$$

Then:

$$s \models \diamond \text{Bad} \quad \text{iff} \quad s \in \Phi^\omega(\emptyset) \quad \text{iff} \quad s \in \text{lfp}.\Phi$$

If  $\Phi(F) \leq F$ , then  $F$  is an **inductive invariant**.

$$\text{MC} = (S, s_I, P) \quad \text{Bad} \subseteq S \quad \lambda \in [0,1]$$

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$$F \leq F' \quad \text{iff} \quad \forall s: F[s] \leq F'[s] .$$

$$\Phi: [0,1]^S \rightarrow [0,1]^S ,$$

$$\Phi(F)[s] = \begin{cases} 1, & \text{if } s \in \text{Bad} \\ \sum_{s' \in S} P(s, s') \cdot F[s'], & \text{else} \end{cases}$$

Then:

$$\Pr (s \models \diamond \text{Bad}) = (\Phi^\omega(\mathbf{0}))[s] = (\text{lfp}.\Phi)[s]$$

If  $\Phi(F) \leq F$ , then  $F$  is an **inductive invariant**.

# The Theory underlying (reverse) IC3: The IC3 Invariants

$$\text{TS} = (S, s_I, T) \quad \text{Bad} \subseteq S$$

Call  $F: S \rightarrow \{0,1\}$  a **frame**.

For increasing  $k = 0, 1, \dots$ , compute sequence

$$F_0, \dots, F_k$$

such that

1. Initiality:  $F_0 = [\text{Bad}] = \Phi(\emptyset)$
2. Chain-Property:  $\forall 0 \leq i < k: F_i \leq F_{i+1}$
3. Frame-safety:  $\forall 0 \leq i \leq k: F_i[s_I] = 0$
4. Relative inductivity:  $\forall 0 \leq i < k: \Phi(F_i) \leq F_{i+1}$

- $\diamond^{\leq i} \text{Bad} \leq F_i$
- If  $F_i = F_{i+1}$ , then  
 $\Phi(F_i) \leq F_i$  hence  $s_I \not\models \diamond \text{Bad}$

# The Theory underlying PrIC3: The PrIC3 Invariants

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2. Chain-Property:  $\forall 0 \leq i < k: F_i \leq F_{i+1}$
3. **Frame-safety**:  $\forall 0 \leq i \leq k: F_i[s_I] \leq \lambda$
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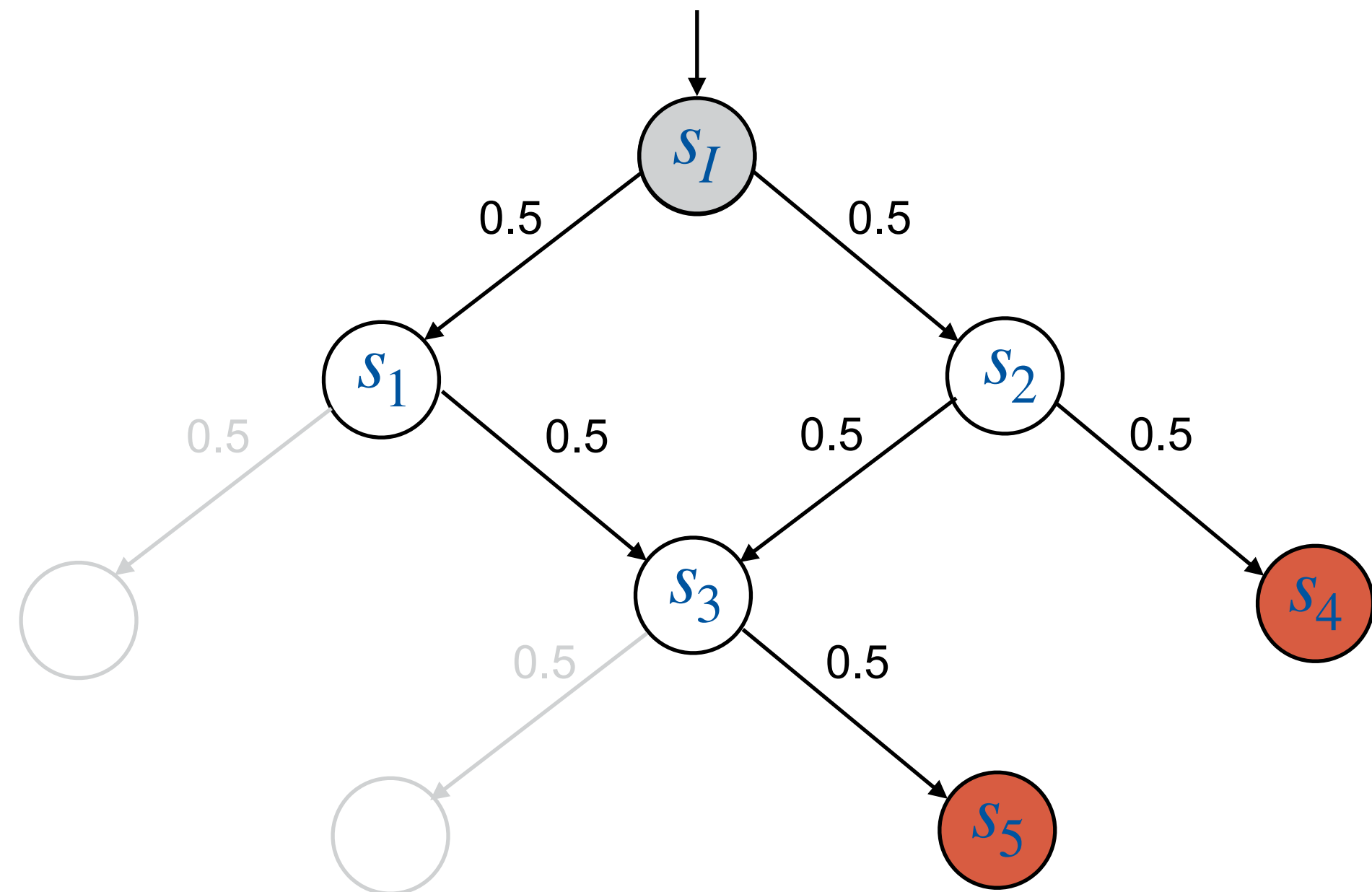
- $\text{Pr}(s \models \Diamond^{\leq i} \text{Bad}) \leq F_i[s]$

- If  $F_i = F_{i+1}$ , then

$$\Phi(F_i) \leq F_i \text{ hence } \text{Pr}(s_I \models \Diamond \text{Bad}) \leq \lambda$$

$$MC = (S, s_I, P) \quad \text{Bad} \subseteq S \quad \lambda = 0.7$$

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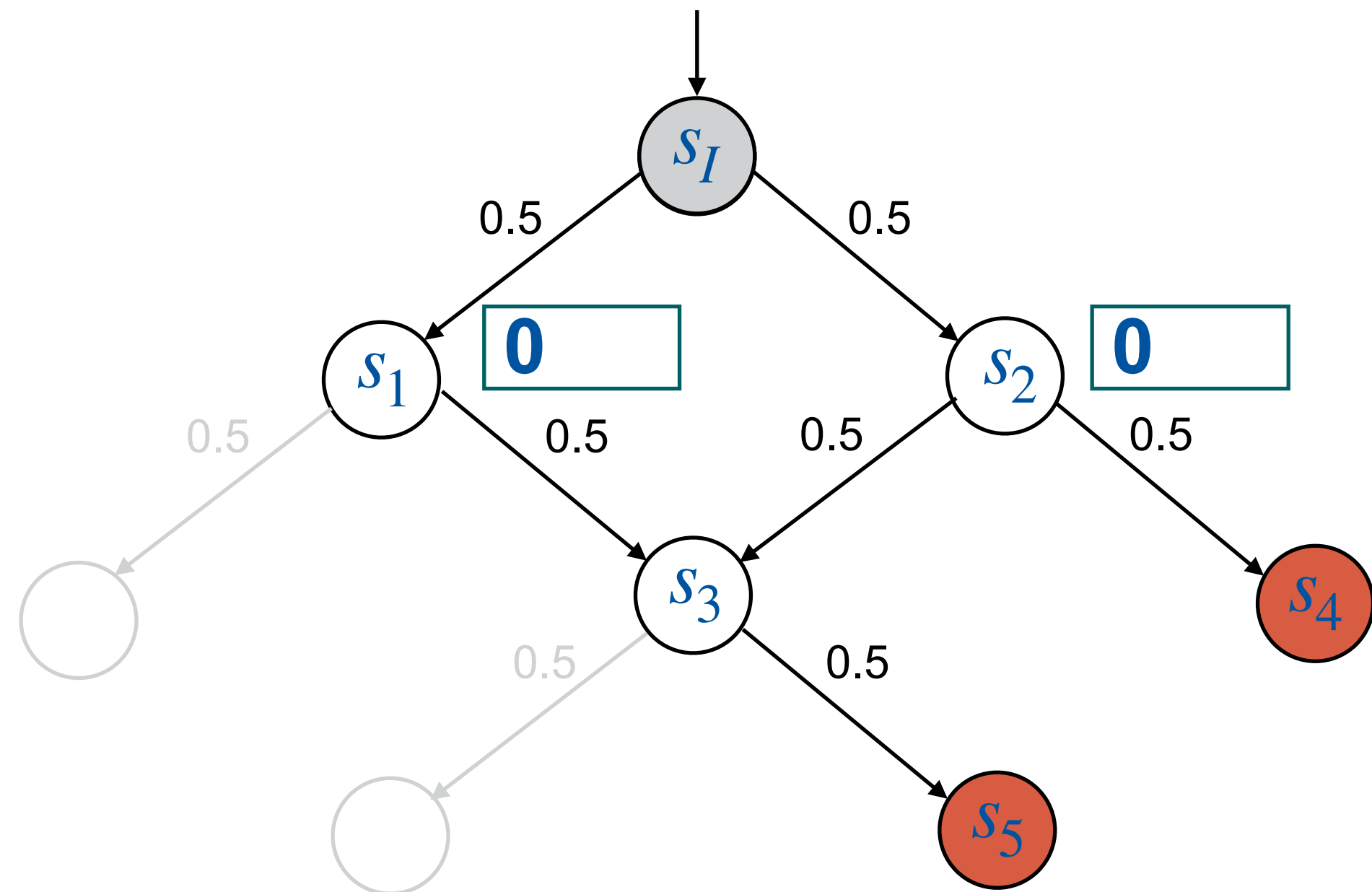
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Check:  $0.5 \cdot F_0[s_1] + 0.5 \cdot F_0[s_2] > 0.7$  ?



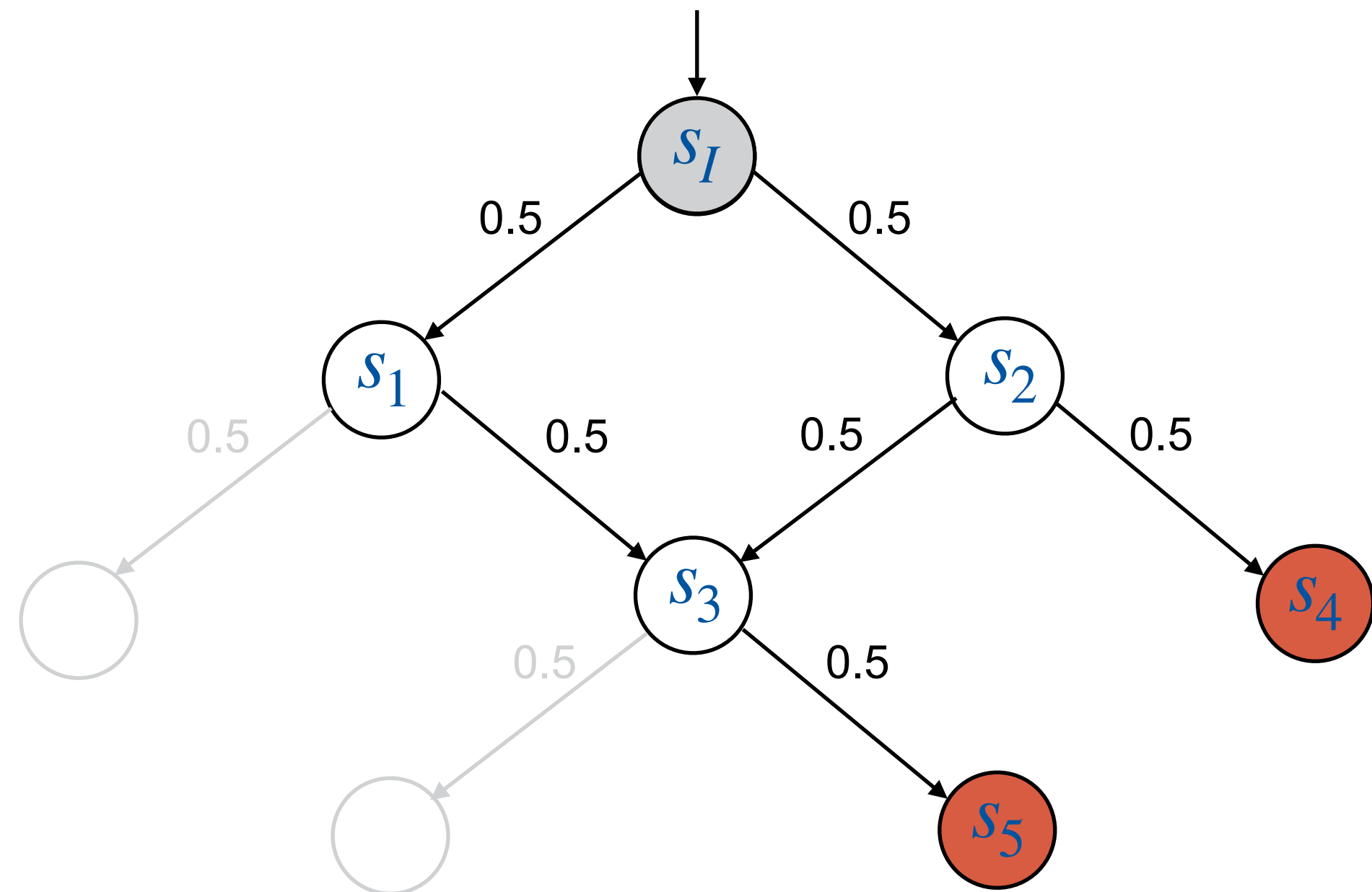
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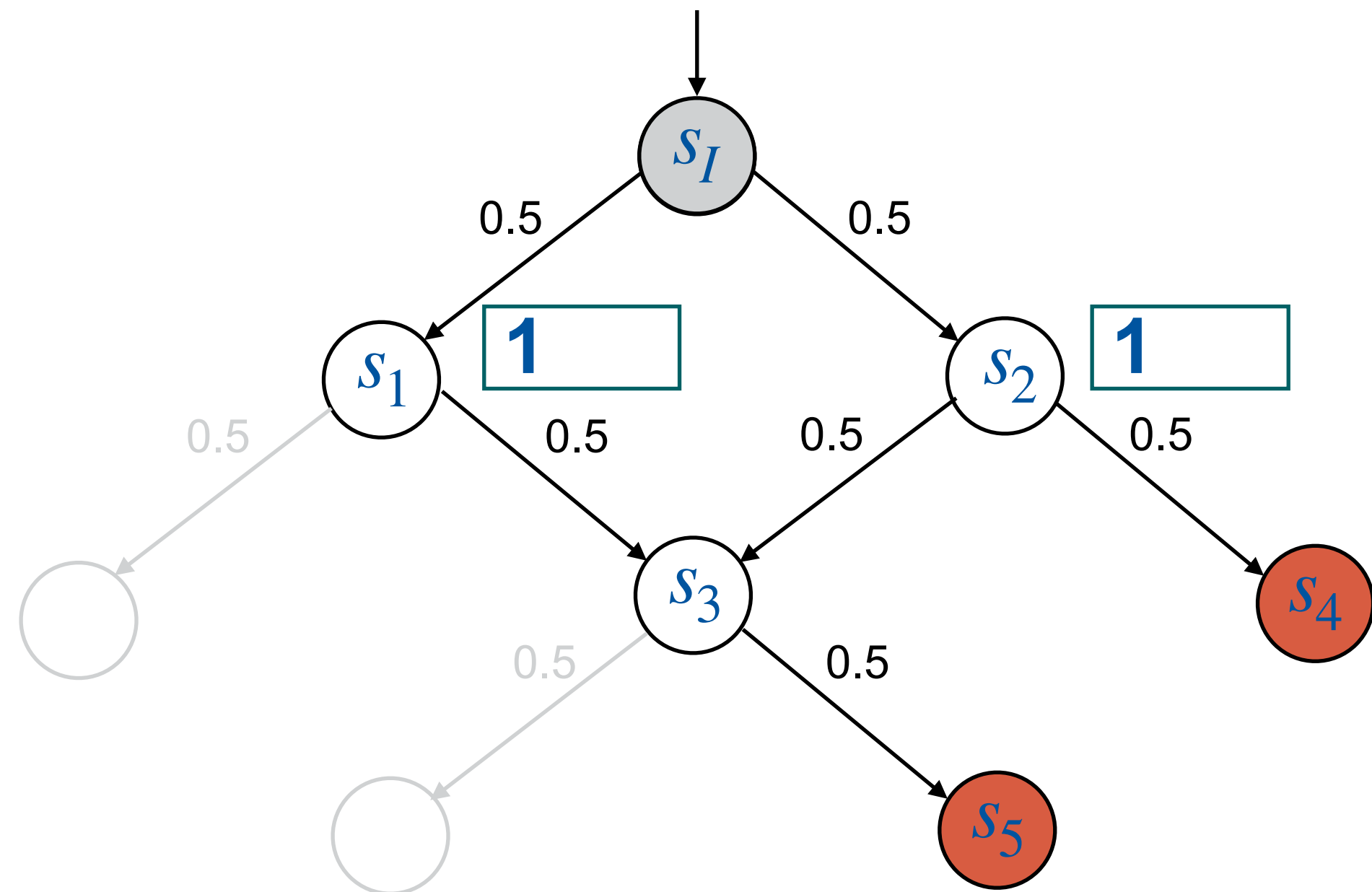
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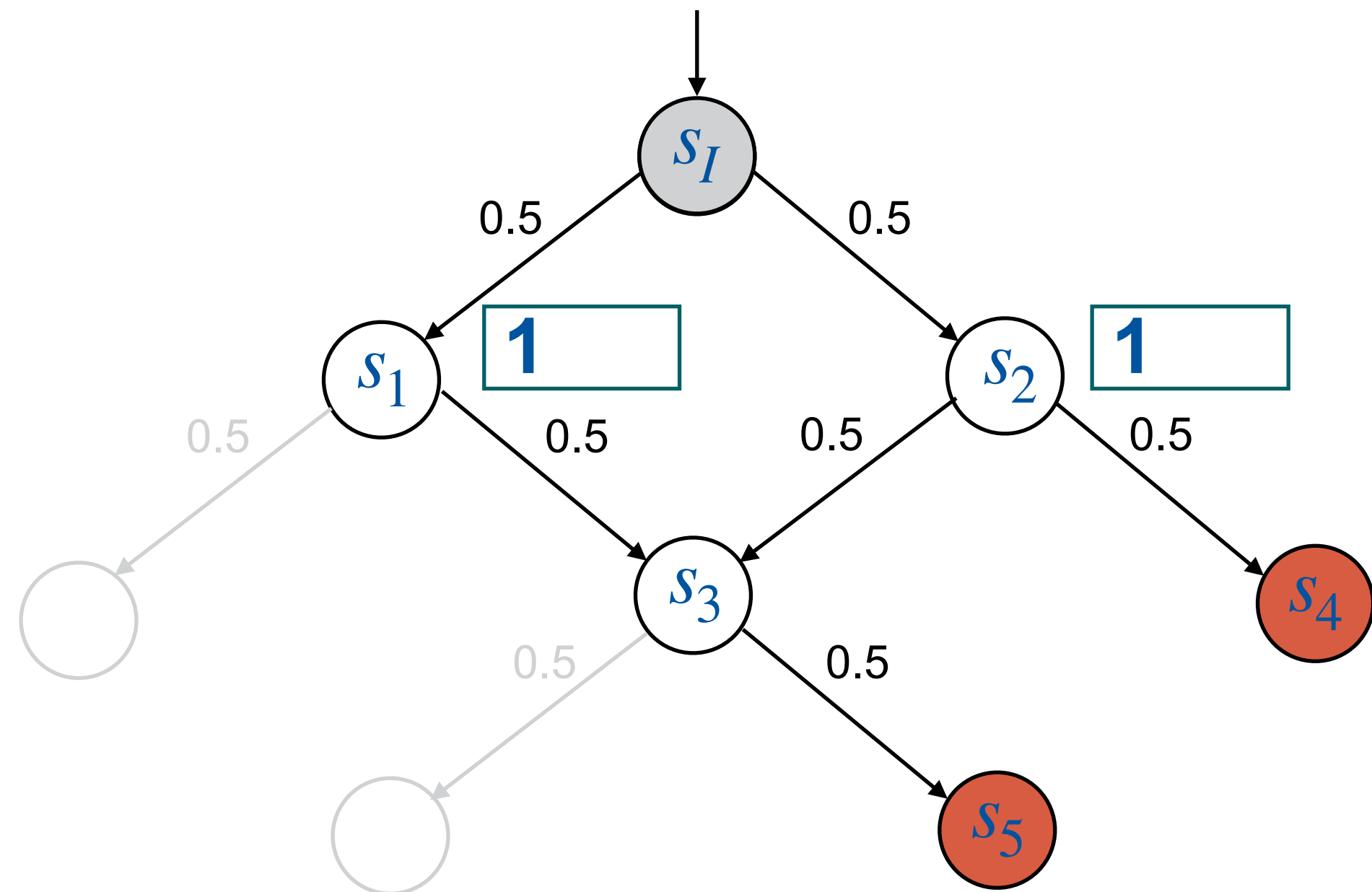
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Find  $x_1, x_2 \in [0, 1]$  such that  
 $0.5 \cdot x_1 + 0.5 \cdot x_2 \leq 0.7$

Problem: Infinitely many choices.  
 There are “bad” choices.  
 Requires heuristic/oracle.

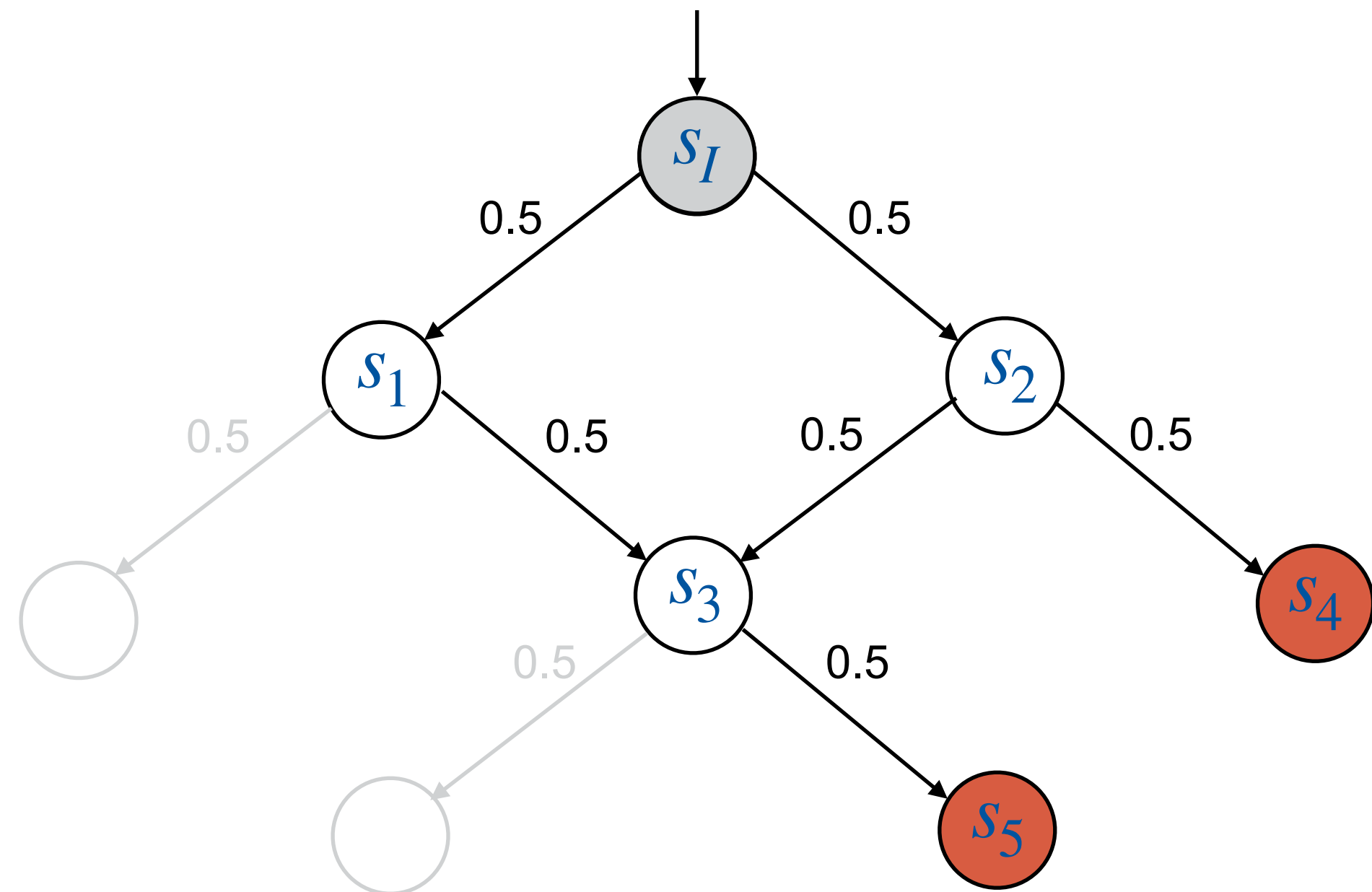
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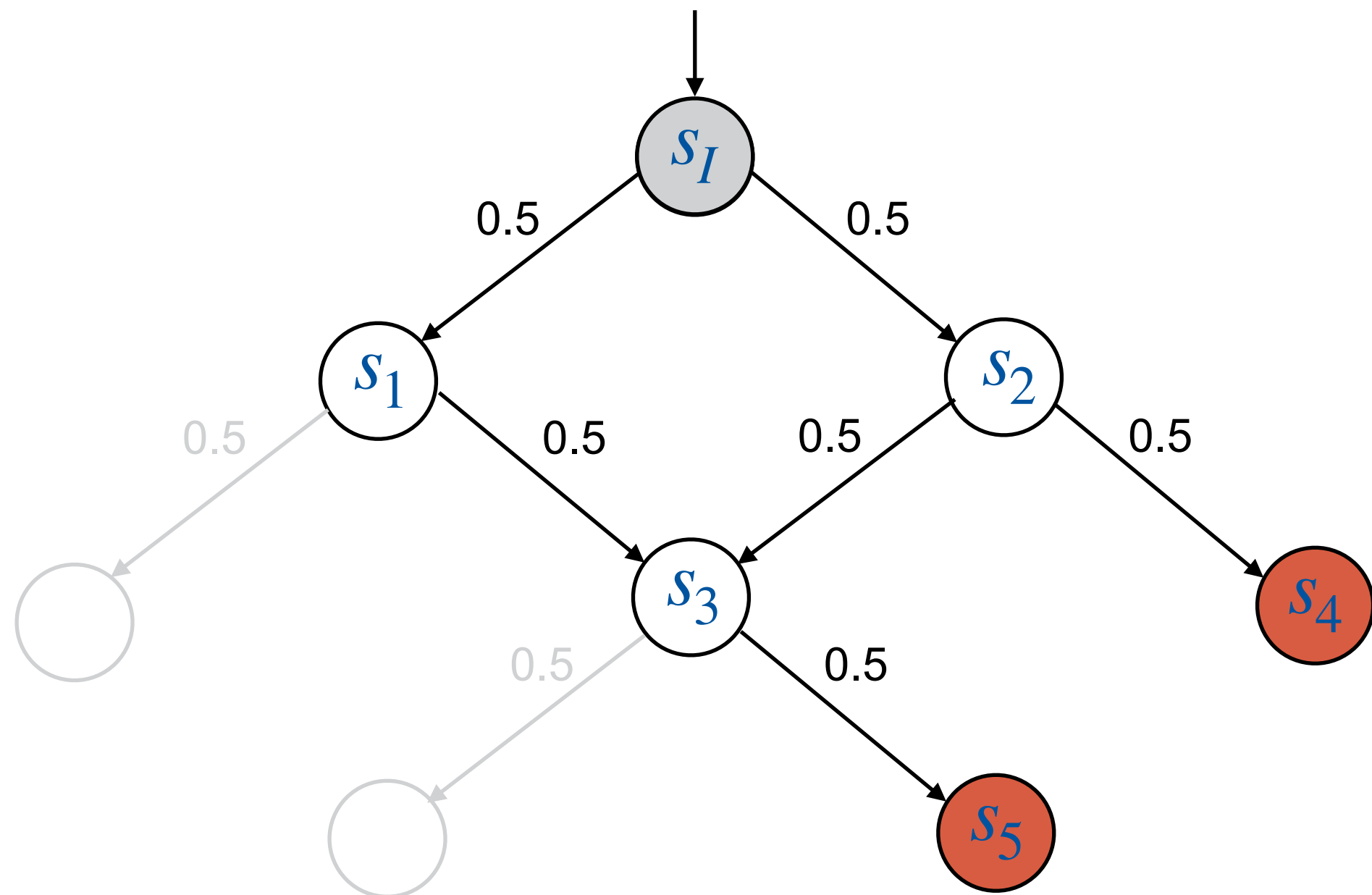
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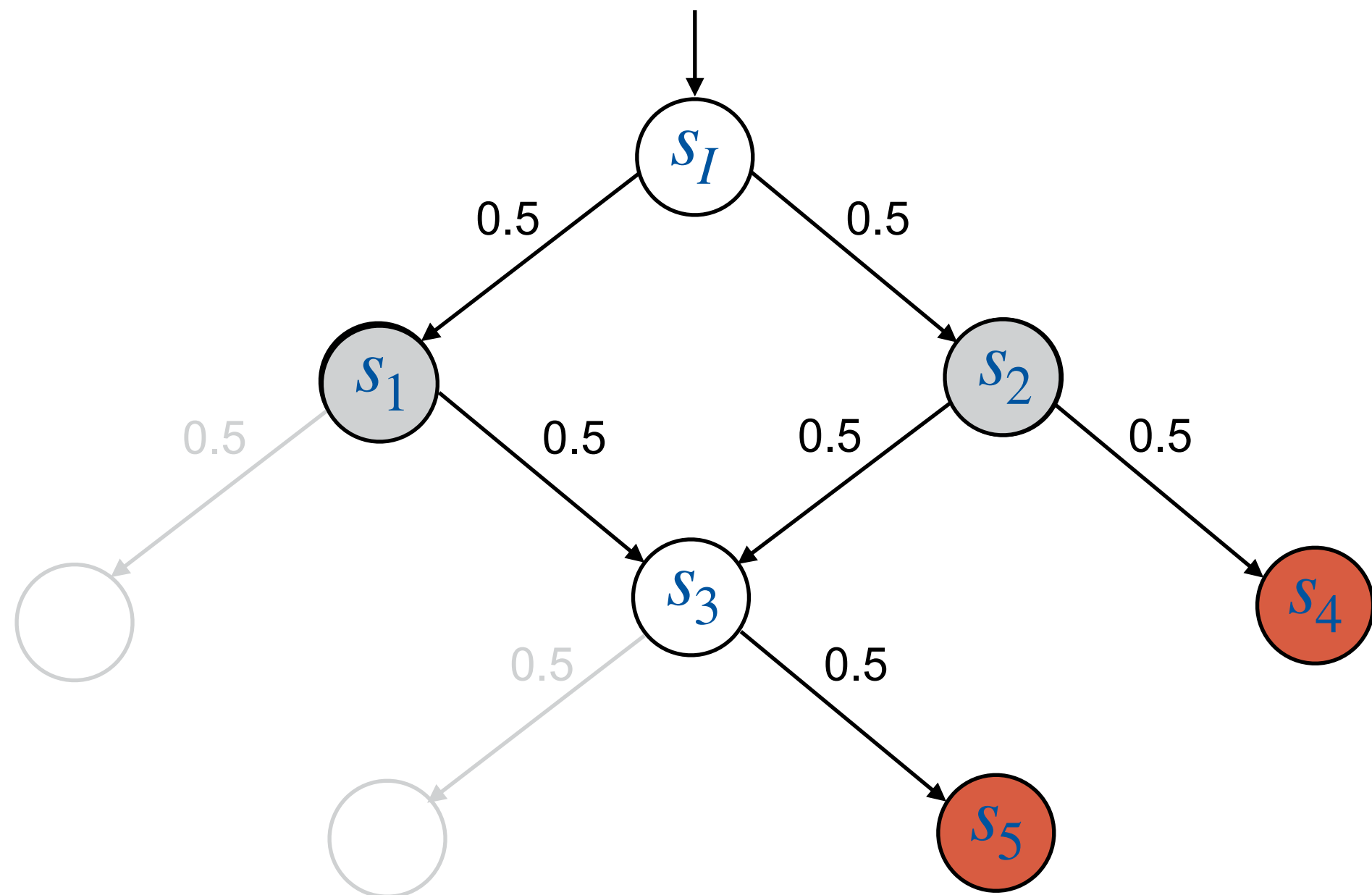
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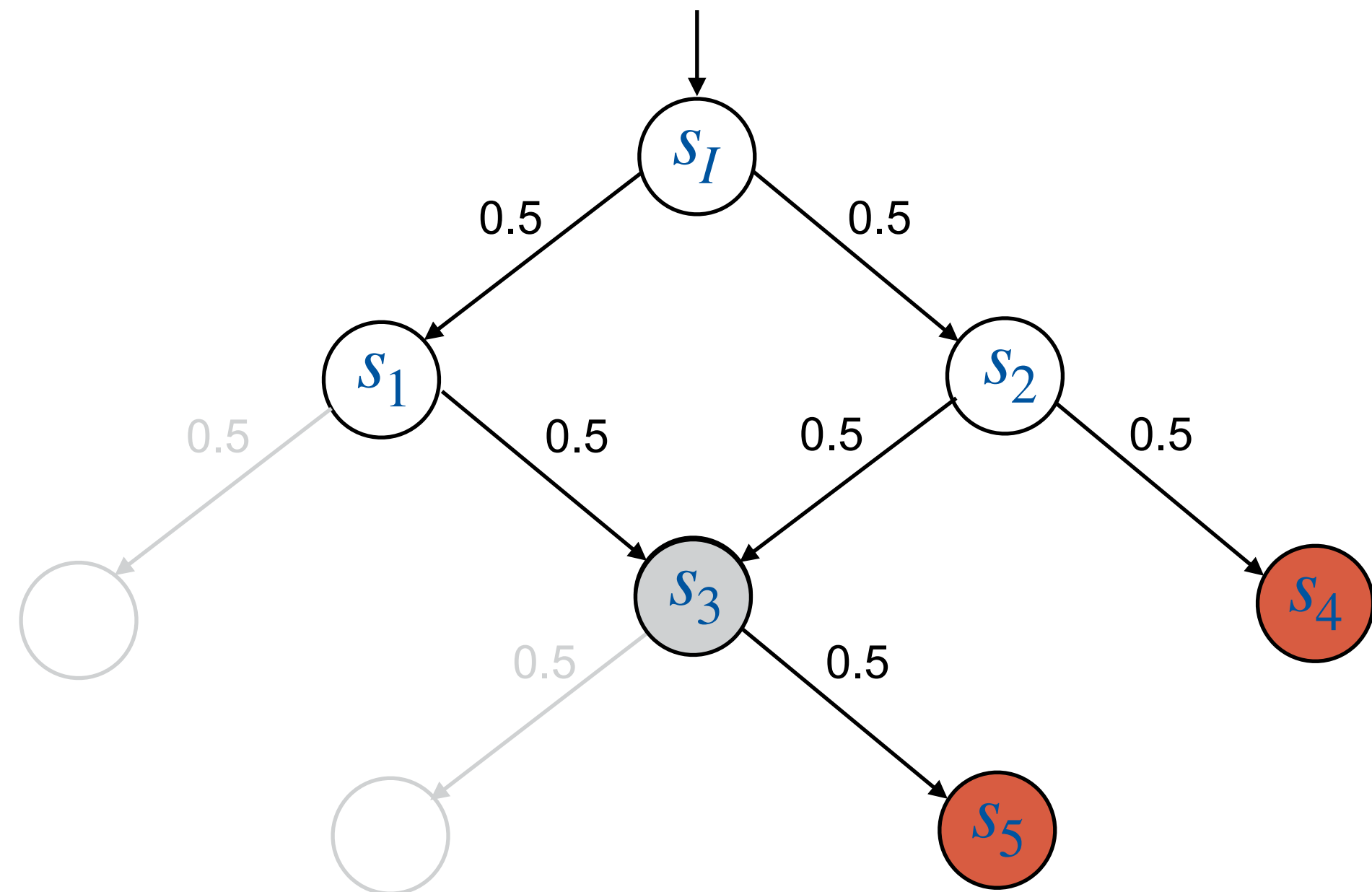
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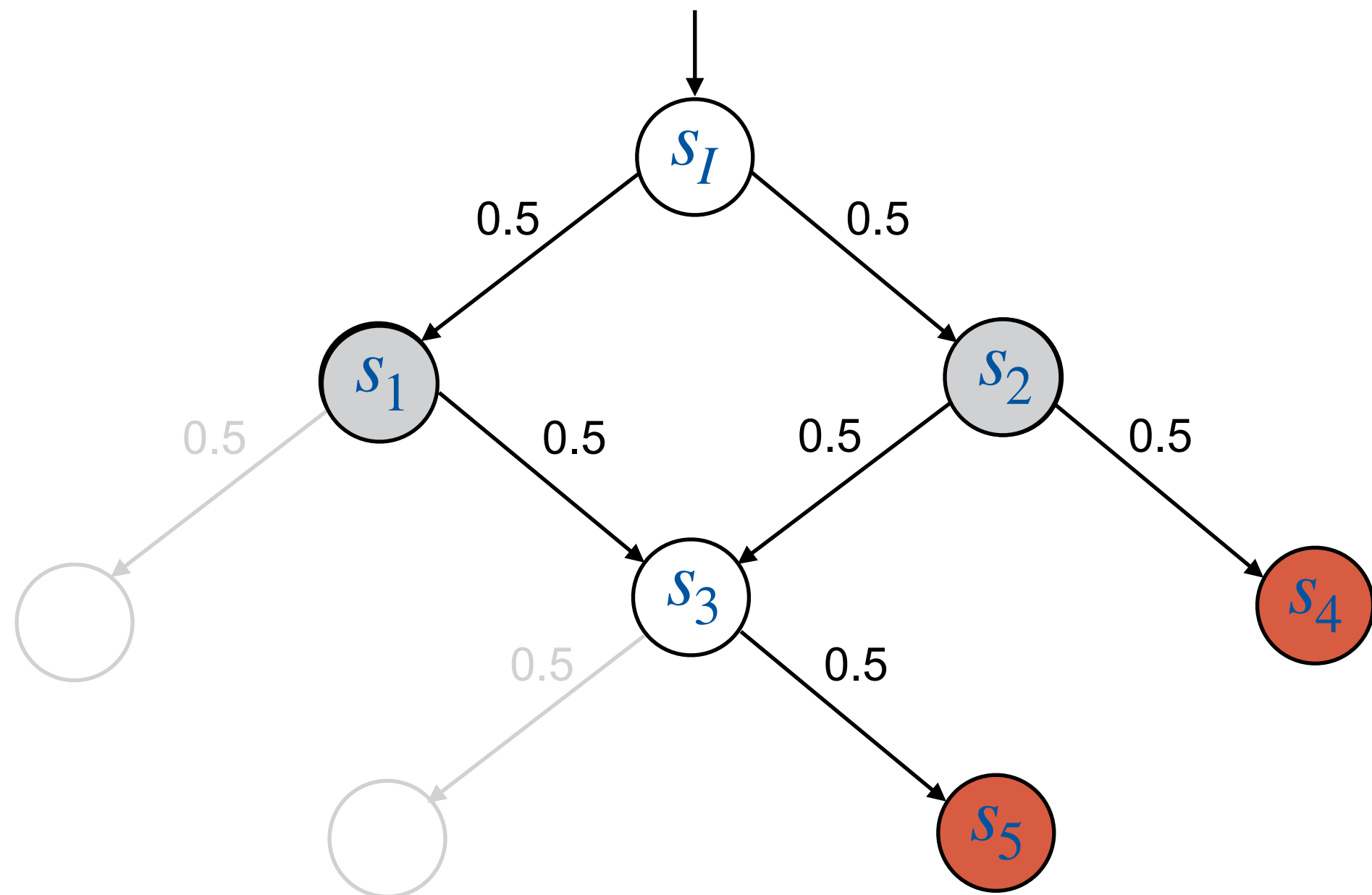
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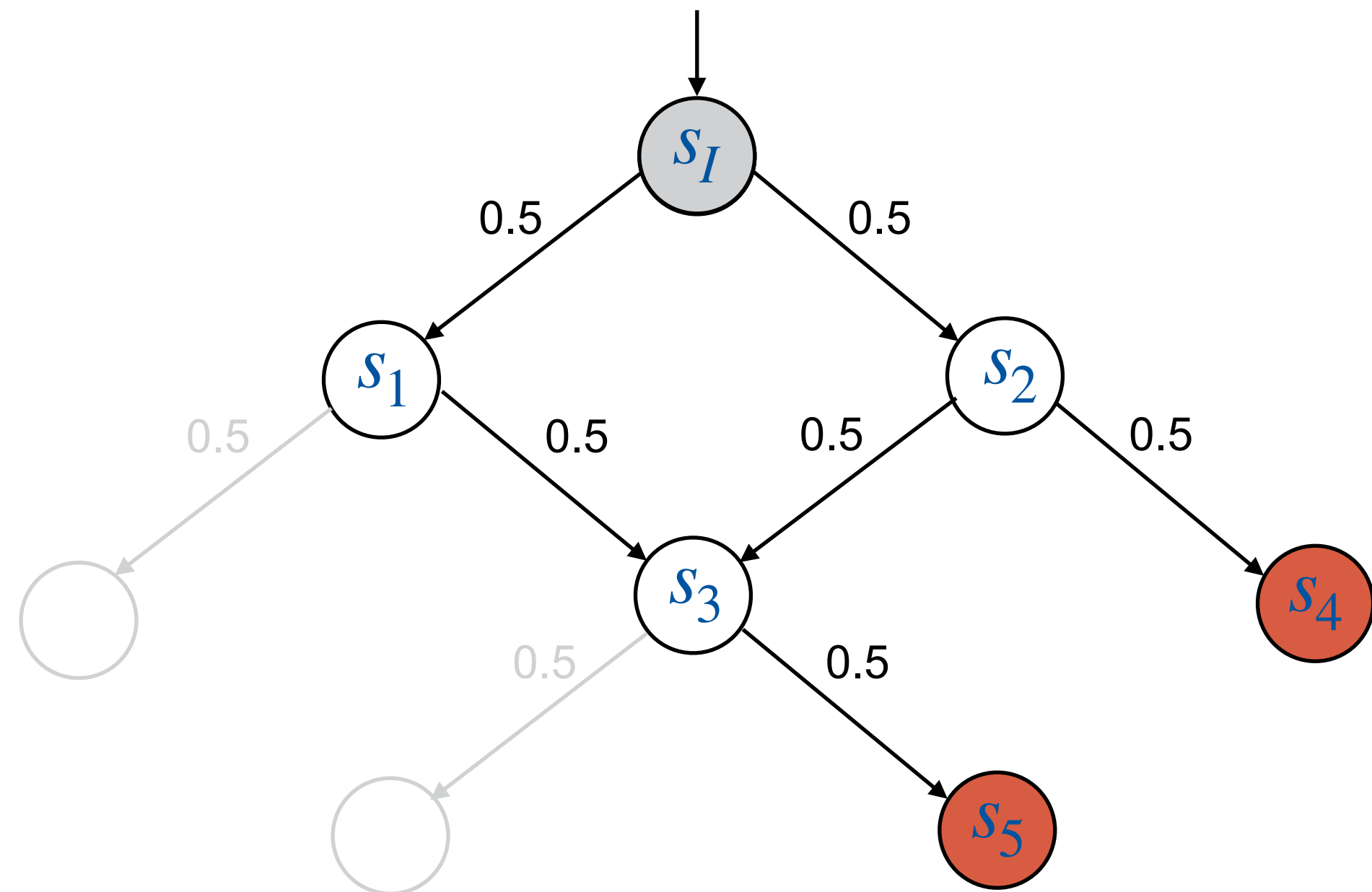
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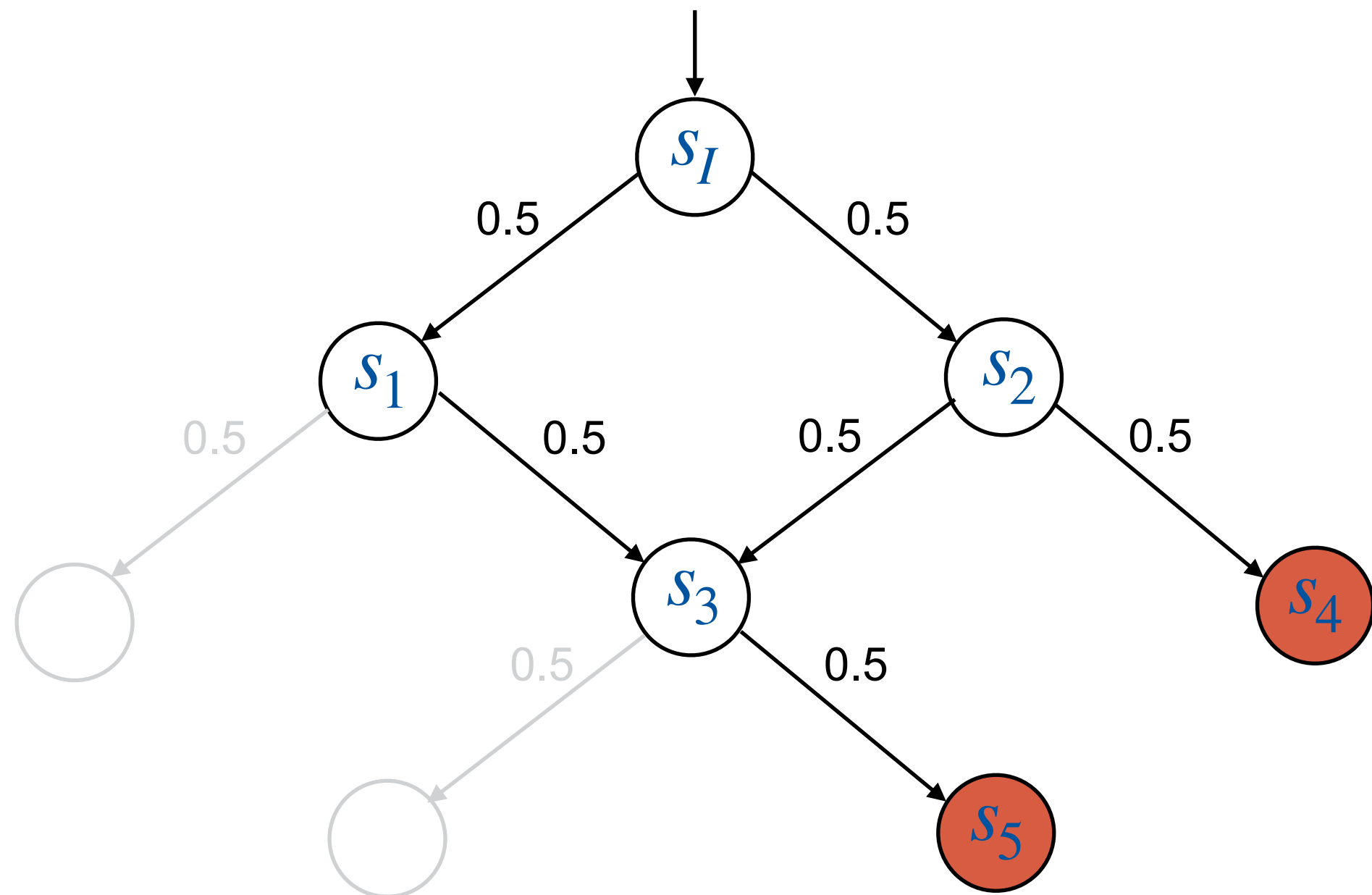
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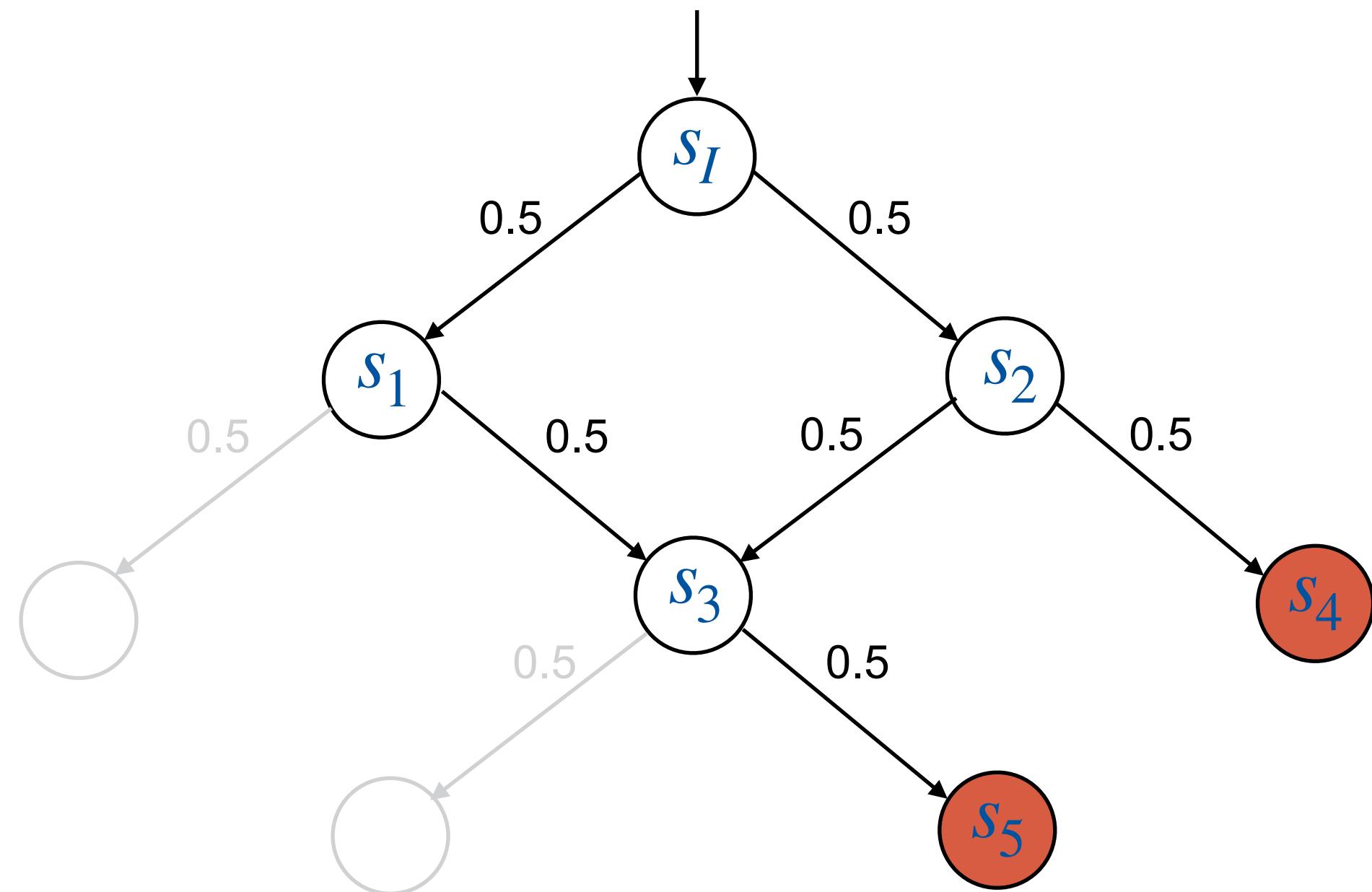
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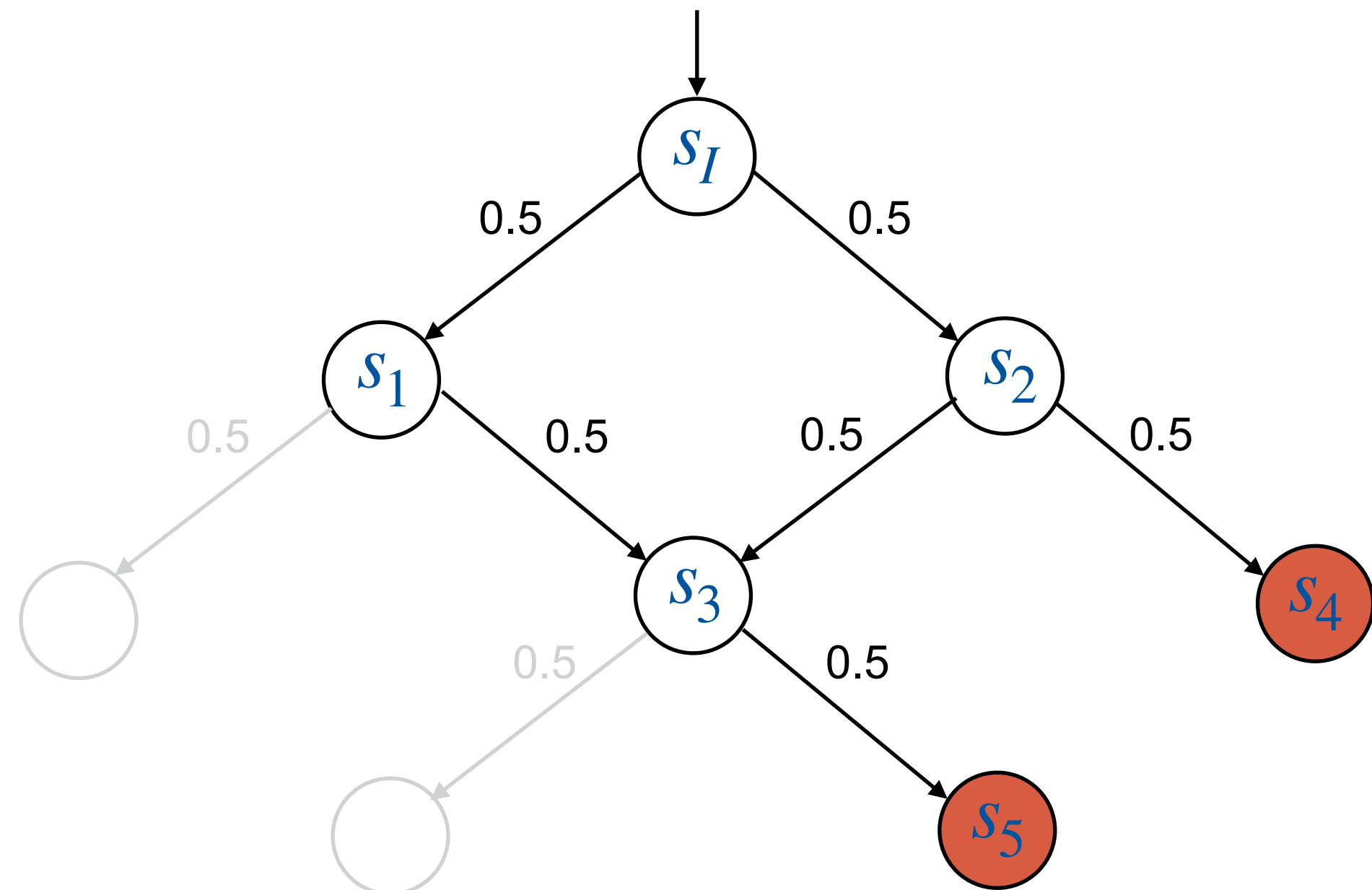
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| 4. Relative inductivity: | $\forall 0 \leq i < k: \Phi(F_i) \leq F_{i+1}$ |



$$F_4 = ( \begin{matrix} & s_I & s_1 & s_2 & s_3 & s_4 & s_5 \\ & 0.7 & 1 & 1 & 1 & 1 & 1 \end{matrix} )$$

$$F_3 = ( \begin{matrix} & s_I & s_1 & s_2 & s_3 & s_4 & s_5 \\ & 0.7 & 0.4 & 1 & 1 & 1 & 1 \end{matrix} )$$

$$F_2 = ( \begin{matrix} & s_I & s_1 & s_2 & s_3 & s_4 & s_5 \\ & 0.7 & 0.4 & 1 & 0.8 & 1 & 1 \end{matrix} )$$

$$F_1 = ( \begin{matrix} & s_I & s_1 & s_2 & s_3 & s_4 & s_5 \\ & 0.7 & 0.4 & 1 & 0.8 & 1 & 1 \end{matrix} )$$

$$F_0(s) = \begin{cases} 0, & \text{if } s \notin \text{Bad} \\ 1, & \text{if } s \in \text{Bad} \end{cases}$$

# Empirical Results

**Table 1.** Empirical results. Run times are in seconds; time out = 15 minutes.

	$ S $	$\Pr^{\max}(s_I \models \diamond B)$	$\lambda$	w/o	$ sub $	pol	$ sub $	Storm <sub>sparse</sub>	Storm <sub>dd</sub>
BRP	$10^3$	0.035	0.01	<b>51.3</b>	324	TO	–	<0.1	0.18
			0.005	<b>10.9</b>	188	TO	–	<0.1	0.1
ZeroConf	$10^9$	~0.55	0.9	TO	–	<b>3.7</b>	0	MO	TO
			0.75	TO	–	<b>3.4</b>	0	MO	TO
			0.52	TO	–	TO	–	MO	TO
			0.45	< <b>0.1</b>	1	< <b>0.1</b>	1	MO	TO
Chain	$10^{12}$	0.394	0.9	TO	–	<b>6.4</b>	0	MO	TO
			0.4	TO	–	<b>6.0</b>	0	MO	TO

<http://www.stormchecker.org/>

<http://qcomp.org/>

# Advanced PrIC3 Challenges

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- Refutation
  - Single paths from  $s_I$  to **Bad** do generally not suffice
- SMT Encoding
- How to find oracles?
  - Solve an abstraction of the state space
  - Compute Q-Table with deep RL
  - Explore part of the system
  - Do some iterations of Value iteration with BDDs

See paper for further reading.

### Conclusion

- PrIC3: A **truly quantitative** extension of IC3
  - Probabilistic invariants
  - PrIC3 invariants
  - PrIC3 requires a heuristic

**Thanks!**

### Future Work

- Finding **good heuristics/oracles**
- **Generalization**
- **Infinite systems?**